# Strong Unique Continuation of Sub-elliptic Operator on the Heisenberg Group* 

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#### Abstract

In this paper, the Almgren's frequency function of the following sub-elliptic equation with singular potential on the Heisenberg group: $$
-\mathcal{L} u+V(z, t) u=-X_{i}\left(a_{i j}(z, t) X_{j} u\right)+V(z, t) u=0
$$ is introduced. The monotonicity property of the frequency is established and a doubling condition is obtained. Consequently, a quantitative proof of the strong unique continuation property for such equation is given.


Keywords Heisenberg group, Frequency function, Doubling condition, Strong unique continuation principle
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## 1 Introduction

The Heisenberg group $H^{n}$ is a nilpotent Lie group of step two whose underlying manifold is $R^{2 n} \times R$ with coordinates $(z, t)=(x, y, t)=\left(x_{1}, \cdots, x_{n}, y_{1}, \cdots, y_{n}, t\right)$ and its group action $\circ$ is given by

$$
\begin{equation*}
\left(x_{0}, y_{0}, t_{0}\right) \circ(x, y, t)=\left(x+x_{0}, y+y_{0}, t+t_{0}+2 \sum_{i=1}^{n}\left(x_{i} y_{0_{i}}-y_{i} x_{0_{i}}\right)\right) \tag{1.1}
\end{equation*}
$$

A basis for the Lie algebra of left-invariant vector fields on $H^{n}$ is given by

$$
\left\{\begin{array}{l}
X_{i}=\frac{\partial}{\partial x_{i}}+2 y_{i} \frac{\partial}{\partial t}, \quad i=1, \cdots, n  \tag{1.2}\\
X_{n+i}=\frac{\partial}{\partial y_{i}}-2 x_{i} \frac{\partial}{\partial t}, \quad i=1, \cdots, n \\
T=\frac{\partial}{\partial t}
\end{array}\right.
$$

From (1.2), it is easy to check that $X_{i}$ and $X_{n+j}$ satisfy

$$
\left[X_{i}, X_{n+j}\right]=-4 T \delta_{i j}, \quad\left[X_{i}, X_{j}\right]=\left[X_{n+i}, X_{n+j}\right]=0, \quad i, j=1, \cdots, n
$$

[^0]Therefore, the vector fields $X_{i}, X_{n+i}(i=1, \cdots, n)$ and their first order commutators span the whole Lie algebra. The horizontal gradient of a function $f$ is defined as

$$
\nabla_{H^{n}} f=X f=\left(X_{1} f, \cdots, X_{n} f, X_{n+1} f, \cdots, X_{2 n} f\right)
$$

Let us denote by $\delta_{\lambda}$ the Heisenberg group dilation

$$
\begin{equation*}
\delta_{\lambda}(x, y, t)=\left(\lambda x, \lambda y, \lambda^{2} t\right), \quad \lambda>0 \tag{1.3}
\end{equation*}
$$

which leads to a homogeneous dimension $Q=2 n+2$.
For $(z, t) \in H^{n}$, we define the gauge norm from the origin

$$
\begin{equation*}
d(z, t)=\left[\left(\sum_{i=1}^{n}\left(x_{i}^{2}+y_{i}^{2}\right)\right)^{2}+t^{2}\right]^{\frac{1}{4}} \equiv\left(|z|^{4}+t^{2}\right)^{\frac{1}{4}} \tag{1.4}
\end{equation*}
$$

which satisfies $d\left(\delta_{\lambda}(z, t)\right)=\lambda d(z, t)$, and means that $d$ is homogeneous of degree one with respect to the dilation $\delta_{\lambda}$ (see $[4,17,19]$ ).

In the sequel, we let

$$
B_{r}=\left\{(z, t) \in H^{n} \mid d(z, t)<r\right\}, \quad \partial B_{r}=\left\{(z, t) \in H^{n} \mid d(z, t)=r\right\}
$$

and call these sets a Heisenberg-ball and a sphere centered at the origin with radius $r$ respectively. Since $d \in C^{\infty}\left(H^{n} \backslash\{(0,0)\}\right)$, the outer unit normal on $\partial B_{r}$ is given by $\vec{n}=|\nabla d|^{-1} \nabla d$, where $\nabla d$ means the ordinary Euclidean gradient of $d$.

Introducing the function

$$
\begin{equation*}
\psi(z, t)=\left|\nabla_{H^{n}} d\right|^{2}=\frac{|z|^{2}}{d(z, t)^{2}} \tag{1.5}
\end{equation*}
$$

we define

$$
\left|B_{r}\right|=\int_{B_{r}} \psi \mathrm{~d} z \mathrm{~d} t \quad \text { and } \quad\left|\partial B_{r}\right|=\frac{\mathrm{d}}{\mathrm{~d} r}\left|B_{r}\right|
$$

Using the polar coordinates adapted to $H^{n}$ introduced by Greiner [12], it is easy to obtain that there exists a constant $\omega_{Q}>0$ depending only on $Q$ such that

$$
\begin{equation*}
\left|B_{r}\right|=\omega_{Q} r^{Q} \tag{1.6}
\end{equation*}
$$

The Kohn-Laplacian on $H^{n}$ is

$$
\Delta_{H^{n}}=\sum_{i=1}^{2 n} X_{i}^{2}
$$

which is the sum of squares of vector fields. Since Hörmander's work [13], the study of operators of the type sum of squares of vector fields has received a strong impetus. Among the large body of literature dedicated to sub-elliptic operators and Carnot-Caratheodory geometry, we briefly recall Bony [5], Folland and Stein [7], Rothschild and Stein [17], Nagel, Stein and Wainger [16], Sanchez-Calle [18] and Jerison [14]. The sub-elliptic operators have a wide range of applications, from several complex variables and CR geometry (see for instance [7]) to control theory and financial mathematics (see for instance [3, 11]).

In this paper, we study the strong unique continuation property of the following sub-elliptic equation on $B_{R_{0}} \subset H^{n}$ :

$$
\begin{equation*}
-\mathcal{L} u+V(z, t) u=-\sum_{i, j=1}^{2 n} X_{i}\left(a_{i j}(z, t) X_{j} u\right)+V(z, t) u=0 \tag{1.7}
\end{equation*}
$$

Our main concern is whether, under suitable assumptions on the coefficients ( $a_{i j}$ ) and the potential $V$, the strong unique continuation property holds for the equation (1.7).

We assume that $A=\left(a_{i j}(z, t)\right)$ is a $2 n \times 2 n$ matrix-valued function on $B_{R_{0}}$, and for simplicity, we assume that $A(0)=I$ (note that this assumption really involves with no loss of generality, because we can always achieve it with a suitable linear transformation, provided that the original equation is at least elliptic at 0$)$. We shall denote by $B$ the matrix

$$
B=A-I_{2 n \times 2 n}
$$

Furthermore, we assume that $A$ is symmetric and satisfies the following hypotheses:
(i) There exist $0<\lambda \leq \Lambda<\infty$ such that for any $\eta \in R^{2 n}$,

$$
\begin{equation*}
\lambda|\eta|^{2} \leq \sum_{i . j=1}^{2 n} a_{i j} \eta_{i} \eta_{j} \leq \Lambda|\eta|^{2} \tag{1.8}
\end{equation*}
$$

(ii) There exist positive constants $C_{1}$ and $C_{2}$ such that

$$
\begin{cases}\left|b_{i j}\right| \equiv\left|a_{i j}-\delta_{i j}\right| \leq C_{1} \psi d, & i, j=1, \cdots, 2 n  \tag{1.9}\\ \left|X_{k} a_{i j}\right| \leq C_{2} \psi^{\frac{1}{2}}, & i, j, k=1, \cdots, 2 n .\end{cases}
$$

We note that the condition (1.9) means that $a_{i j}$ is $\psi$-Lipschitz.
We require that the potential $V$ in (1.7) satisfies the following assumption: There exist a constant $M>0$ and an increasing function $f:\left(0, R_{0}\right) \rightarrow R^{+}$such that

$$
\begin{equation*}
\int_{0}^{R_{0}} \frac{f(r)}{r} \mathrm{~d} r<\infty \tag{1.10}
\end{equation*}
$$

for which

$$
\begin{equation*}
|V(z, t)| \leq M \frac{f(d(z, t))}{d(z, t)^{2}} \psi(z, t) \quad \text { for a.e. }(z, t) \in B_{R_{0}} \tag{1.11}
\end{equation*}
$$

According to (1.10)-(1.11), the potential $V$ is allowed to be singular (see [8]).
We need to introduce the following definitions.
Definition 1.1 A weak solution to (1.7) is a function $u \in C\left(B_{R_{0}}\right) \cap L^{2}\left(B_{R_{0}}\right)$ such that the horizontal gradient $X u \in L^{2}\left(B_{R_{0}}\right)$, and (1.7) is satisfied in the distribution sense, i.e.,

$$
\int_{B_{R_{0}}} a_{i j} X_{i} u X_{j} \phi \mathrm{~d} z \mathrm{~d} t+\int_{B_{R_{0}}} V u \phi \mathrm{~d} z \mathrm{~d} t=0
$$

for every $\phi \in C_{0}^{\infty}\left(B_{R_{0}}\right)$.
Definition 1.2 We say that $u$ is polyradial in $H^{n}$ if for any $(z, t)=\left(z_{1}, \cdots, z_{n}, t\right) \in H^{n}$ where $z_{j}=x_{j}+i y_{j}$ and $\left|z_{j}\right|=\left(x_{j}^{2}+y_{j}^{2}\right)^{\frac{1}{2}}$, we have $u(z, t)=u^{*}\left(\left|z_{1}\right|, \cdots,\left|z_{n}\right|, t\right)$ for some $u^{*}$.

Definition 1.3 We say that $u \in L^{2}\left(B_{R_{0}}\right)$ vanishes up to infinite order at the origin, if for every $k>0$ one has

$$
\lim _{r \rightarrow 0} \frac{1}{r^{k}} \int_{B_{r}} u^{2} \psi \mathrm{~d} z \mathrm{~d} t=0
$$

We are ready to state our main results.

Theorem 1.1 Let $V$ satisfy (1.11) for some $M$ and $f, A$ be a symmetric matrix satisfying (1.8)-(1.9), and $u$ be a polyradial solution to (1.7) in $B_{R_{0}}$. Then there exist positive constants $\Gamma=\Gamma(u, \lambda, \Lambda)$ and $r_{0}=r_{0}(\lambda, \Lambda)$, such that for any $2 r \leq r_{0}$, we have

$$
\begin{equation*}
\int_{B_{2 r}} u^{2} \psi \mathrm{~d} z \mathrm{~d} t \leq \Gamma \int_{B_{r}} u^{2} \psi \mathrm{~d} z \mathrm{~d} t \tag{1.12}
\end{equation*}
$$

Note that (1.12) is often referred to as the doubling condition and it yields quantitative information on the vanishing order at the origin of $u$. As well-known (see [8-9] and etc.), Theorem 1.1 implies the following strong unique continuation property.

Theorem 1.2 With the assumptions of the Theorem 1.1, if $u$ vanishes up to infinite order at the origin, then $u \equiv 0$ in $B_{r_{0}}$, where $r_{0}$ is as in the statement of Theorem 1.1.

We mention that when the horizontal gradient is replaced by the classical gradient on $R^{n}$, i.e.,

$$
\begin{equation*}
\sum_{i, j=1}^{n} \frac{\partial}{\partial x_{i}}\left(a_{i j}(x) \frac{\partial u}{\partial x_{j}}\right)=0 \tag{1.13}
\end{equation*}
$$

a result due to [2] states that if the matrix $\left(a_{i j}\right)$ is Lipschitz continuous, then the equation (1.13) possesses the strong unique continuation property. Furthermore, it was shown in [15] that the Lipschitz continuous assumption on the coefficients is optimal. Our results can be seen as a generalization of those in [2]. The approach, however, is different from that in [2], which is based on Carleman inequalities that do not seem to be adaptable to our operator due to the lack of ellipticity. Instead, we have used the ideas of Almgren's frequency function that goes back to Almgren [1] and has been developed in [8-10].

We note that when $a_{i j}=\delta_{i j}$, the equation (1.7) becomes the Kohn-Laplace equation with potential $V$ on $H^{n}$

$$
\begin{equation*}
-\sum_{i=1}^{2 n} X_{i}^{2} u+V u=0 \tag{1.14}
\end{equation*}
$$

which was studied by Garofalo and Lanconelli [8], under some assumptions of $V$ and with the weak solution $u$, they proved the strong unique continuation property of equation (1.14). So our results can also be seen as a generalization of those in [8]. Because of the variable coefficients, we should overcome more difficulties to obtain the monotonicity of the frequency function by using the refined geometry properties of $H^{n}$.

The rest of the paper is organized as follows. In Section 2, we give some notations and various technical estimates. In Section 3, we introduce the frequency function and prove its monotonicity and the doubling condition, and finally we give the proofs of Theorems 1.1 and 1.2.

## 2 Preliminary Facts

We begin this section by giving some basic facts about the horizontal gradient $\nabla_{H^{n}}$ and the operator $\mathcal{L}$ on $H^{n}$.

We denote by $S$ the $2 n \times(2 n+1)$ matrix relating the horizontal gradient $\nabla_{H^{n}}$ and the standard gradient $\nabla$ in $R^{2 n+1}$, i.e., $\nabla_{H^{n}}=S \cdot \nabla$, where

$$
S=\left(\begin{array}{ccc}
I_{n \times n} & 0_{n \times n} & (2 y)^{\mathrm{T}}  \tag{2.1}\\
0_{n \times n} & I_{n \times n} & (-2 x)^{\mathrm{T}}
\end{array}\right)
$$

Hence we have

$$
\begin{equation*}
\mathcal{L} u=\sum_{i=1}^{2 n} X_{i}\left(a_{i j} X_{j} u\right)=\operatorname{div}\left(S^{\mathrm{T}} A \nabla_{H^{n}} u\right)=\operatorname{div}\left(S^{\mathrm{T}} A S \nabla u\right) \tag{2.2}
\end{equation*}
$$

Now we define a vector field

$$
\begin{equation*}
Z=\sum_{i=1}^{n}\left(x_{i} \frac{\partial}{\partial x_{i}}+y_{i} \frac{\partial}{\partial y_{i}}\right)+2 t \frac{\partial}{\partial t} \tag{2.3}
\end{equation*}
$$

A direct calculation yields

$$
\begin{equation*}
Z u=\frac{d}{\psi} \sum_{i=1}^{2 n} X_{i} d X_{i} u, \quad \text { if } \widetilde{T} u \equiv \sum_{i=1}^{n}\left(y_{i} \frac{\partial u}{\partial x_{i}}-x_{i} \frac{\partial u}{\partial y_{i}}\right)=0 \tag{2.4}
\end{equation*}
$$

Proposition 2.1 Letting $Z$ and $\widetilde{T}$ be the above vector fields on $H^{n}$, we have

$$
\begin{equation*}
\left[X_{i}, Z\right] u=X_{i} u, \quad i=1, \cdots, 2 n \tag{2.5}
\end{equation*}
$$

and

$$
\begin{equation*}
\left|\left[X_{i}, X_{j}\right] u\right| \leq \frac{1}{|z|}|X u|, \quad \text { if } \widetilde{T} u=0, i, j=1, \cdots, 2 n \tag{2.6}
\end{equation*}
$$

Proof By the definitions of the vector fields $X_{i}$ and $Z$, we have

$$
\begin{aligned}
{\left[X_{i}, Z\right] u=} & X_{i} Z u-Z X_{i} u \\
= & \left(\frac{\partial}{\partial x_{i}}+2 y_{i} \frac{\partial}{\partial t}\right)\left(\sum_{k=1}^{n} x_{k} \frac{\partial u}{\partial x_{k}}+y_{k} \frac{\partial u}{\partial y_{k}}+2 t \frac{\partial u}{\partial t}\right) \\
& -\left(\sum_{k=1}^{n} x_{k} \frac{\partial}{\partial x_{k}}+y_{k} \frac{\partial}{\partial y_{k}}+2 t \frac{\partial}{\partial t}\right)\left(\frac{\partial u}{\partial x_{i}}+2 y_{i} \frac{\partial u}{\partial t}\right) \\
= & \sum_{k=1}^{n} \delta_{k i} \frac{\partial u}{\partial x_{k}}+2 \delta_{k i} y_{k} \frac{\partial u}{\partial t}=\frac{\partial u}{\partial x_{i}}+2 y_{i} \frac{\partial u}{\partial t}=X_{i} u
\end{aligned}
$$

for any $u \in C^{\infty}$. Hence $\left[X_{i}, Z\right]=X_{i}$ for $i=1, \cdots, n$.
Similarly, we prove $\left[X_{n+i}, Z\right]=X_{n+i}$ for $i=1, \cdots, n$.
A direct calculation yields

$$
\begin{aligned}
\sum_{i=1}^{n} y_{i} X_{i} u-x_{i} X_{n+i} u & =\sum_{i=1}^{n}\left(y_{i} \frac{\partial u}{\partial x_{i}}-x_{i} \frac{\partial u}{\partial y_{i}}\right)+2 \sum_{i=1}^{n}\left(x_{i}^{2}+y_{i}^{2}\right) \frac{\partial u}{\partial t} \\
& =2|z|^{2} \frac{\partial u}{\partial t}
\end{aligned}
$$

where we use $\widetilde{T} u \equiv \sum_{i=1}^{n}\left(y_{i} \frac{\partial u}{\partial x_{i}}-x_{i} \frac{\partial u}{\partial y_{i}}\right)=0$ in the last equality. Thus

$$
\left|\left[X_{i}, X_{j}\right] u\right| \leq 4\left|\frac{\partial u}{\partial t}\right| \leq \frac{1}{|z|}|X u|
$$

Next we prove some basic estimates that will be used later.

Proposition 2.2 (1) The horizontal derivatives of the distance function $d$ and the angle function $\psi$ satisfy

$$
\begin{aligned}
& \left|X_{i} d\right| \leq C \psi^{\frac{1}{2}}, \quad i=1, \cdots, 2 n \\
& \left|X_{i} \psi\right| \leq C \frac{1}{d} \psi^{\frac{1}{2}}, \quad i=1, \cdots, 2 n
\end{aligned}
$$

(2) The second horizontal derivatives of $d$ satisfy

$$
\begin{aligned}
\left|X_{i} X_{j} d\right| & \leq C \frac{1}{d} \psi, \quad i, j=1, \cdots, n \\
\left|X_{i} X_{n+j} d\right| & \leq C \frac{1}{d}, \quad i, j=1, \cdots, n \\
\left|X_{n+i} X_{j} d\right| & \leq C \frac{1}{d}, \quad i, j=1, \cdots, n \\
\left|X_{n+i} X_{n+j} d\right| & \leq C \frac{1}{d} \psi, \quad i, j=1, \cdots, n
\end{aligned}
$$

and

$$
\sum_{i, j=1}^{2 n} X_{i} d\left(X_{i} X_{j} d\right) X_{j} d=0
$$

Proof By the definitions of $d$ in (1.4) and $\psi$ in (1.5),

$$
\begin{aligned}
X_{i} d & =\left(\frac{\partial}{\partial x_{i}}+2 y_{i} \frac{\partial}{\partial t}\right) d=\frac{1}{d^{3}}\left(|z|^{2} x_{i}+y_{i} t\right), \quad i=1, \cdots, n . \\
X_{n+i} d & =\left(\frac{\partial}{\partial y_{i}}-2 x_{i} \frac{\partial}{\partial t}\right) d=\frac{1}{d^{3}}\left(|z|^{2} y_{i}-x_{i} t\right), \quad i=1, \cdots, n, \\
X_{i} \psi & =X_{i}\left(\frac{|z|^{2}}{d^{2}}\right)=\frac{2 x_{i}}{d^{2}}-\frac{2|z|^{2}}{d^{3}} X_{i} d, \quad i=1, \cdots, n, \\
X_{n+i} \psi & =X_{n+i}\left(\frac{|z|^{2}}{d^{2}}\right)=\frac{2 y_{i}}{d^{2}}-\frac{2|z|^{2}}{d^{3}} X_{n+i} d, \quad i=1, \cdots, n .
\end{aligned}
$$

This shows that

$$
\begin{aligned}
\left|X_{i} d\right| & =\left|\frac{|z|^{2}}{d^{2}} \cdot \frac{x_{i}}{d}+\frac{t}{d^{2}} \cdot \frac{y_{i}}{d}\right| \leq C \psi^{\frac{1}{2}}, \quad i=1, \cdots, n \\
\left|X_{n+i} d\right| & =\left|\frac{|z|^{2}}{d^{2}} \cdot \frac{y_{i}}{d}-\frac{t}{d^{2}} \cdot \frac{x_{i}}{d}\right| \leq C \psi^{\frac{1}{2}}, \quad i=1, \cdots, n
\end{aligned}
$$

and

$$
\left|X_{i} \psi\right| \leq C \frac{1}{d} \psi^{\frac{1}{2}}, \quad i=1, \cdots, 2 n
$$

We continue to compute the second derivative of $d$ and this is done easily by using the product rule. We only write the expressions for the second derivatives

$$
\begin{aligned}
X_{i}\left(X_{j} d\right) & =\frac{2 x_{i} x_{j}+2 y_{i} y_{j}+|z|^{2} \delta_{i j}}{d^{3}}-3 \frac{\left(|z|^{2} x_{i}+y_{i} t\right)\left(|z|^{2} x_{j}+y_{j} t\right)}{d^{7}}, \\
X_{i}\left(X_{n+j} d\right) & =\frac{2 x_{i} y_{j}-2 y_{i} x_{j}-\delta_{i j} t}{d^{3}}-3 \frac{\left(|z|^{2} x_{i}+y_{i} t\right)\left(|z|^{2} y_{j}-x_{j} t\right)}{d^{7}} \\
X_{n+i}\left(X_{j} d\right) & =\frac{2 y_{i} x_{j}-2 x_{i} y_{j}+\delta_{i j} t}{d^{3}}-3 \frac{\left(|z|^{2} y_{i}-x_{i} t\right)\left(|z|^{2} x_{j}+y_{j} t\right)}{d^{7}} \\
X_{n+i}\left(X_{n+j} d\right) & =\frac{2 y_{i} y_{j}+2 x_{i} x_{j}+|z|^{2} \delta_{i j}}{d^{3}}-3 \frac{\left(|z|^{2} y_{i}-x_{i} t\right)\left(|z|^{2} y_{j}-x_{j} t\right)}{d^{7}} .
\end{aligned}
$$

Hence,

$$
\begin{aligned}
\left|X_{i} X_{j} d\right| & \leq C \frac{1}{d} \psi, \quad i, j=1, \cdots, n \\
\left|X_{i} X_{n+j} d\right| & \leq C \frac{1}{d}, \quad i, j=1, \cdots, n \\
\left|X_{n+i} X_{j} d\right| & \leq C \frac{1}{d}, \quad i, j=1, \cdots, n \\
\left|X_{n+i} X_{n+j} d\right| & \leq C \frac{1}{d} \psi, \quad i, j=1, \cdots, n .
\end{aligned}
$$

Finally, with the first and second horizontal derivatives of $d$ in hand, we obtain

$$
\begin{aligned}
& \sum_{i, j=1}^{2 n} X_{i} d\left(X_{i} X_{j} d\right) X_{j} d \\
= & \sum_{i, j=1}^{n}\left[X_{i} d\left(X_{i} X_{j} d\right) X_{j} d+X_{i} d\left(X_{i} X_{n+j} d\right) X_{n+j} d\right. \\
& \left.+X_{n+i} d\left(X_{n+i} X_{j} d\right) X_{j} d+X_{n+i} d\left(X_{n+i} X_{n+j} d\right) X_{n+j} d\right]=0
\end{aligned}
$$

At the end of this section, we give an inequality (see [8, Theorem 2.2]).
Lemma 2.1 For every $u \in C_{0}^{\infty}\left(H^{n} \backslash\{(0,0)\}\right)$ and every $r>0$, we have

$$
\begin{align*}
\int_{B_{r}} \frac{u(z, t)^{2}}{d(z, t)^{2}} \psi(z, t) \mathrm{d} z \mathrm{~d} t \leq & \left(\frac{2}{Q-2}\right)^{2}\left\{\int_{B_{r}}\left|\nabla_{H^{n}} u(z, t)\right|^{2} \mathrm{~d} z \mathrm{~d} t\right. \\
& \left.+\left(\frac{Q-2}{2}\right) \frac{1}{r} \int_{\partial B_{r}} u(z, t)^{2} \frac{\psi(z, t)}{|\nabla d(z, t)|^{2}} \mathrm{~d} H^{2 n}\right\} \tag{2.7}
\end{align*}
$$

## 3 The Frequency Function and Unique Continuation

The purpose of this section is to prove Theorems 1.1 and 1.2. The main step is to show a monotonicity of the frequency function, which was first discovered by Almgren [1]. We begin by introducing the relevant quantities that will appear in the proofs. Hereafter, the summation convention over repeated indices will be adopted.

Definition 3.1 For a weak solution $u$ of (1.7) in $B_{R_{0}}$ and $0<r<R_{0}$, we define its height in $B_{r}$ as follows:

$$
H(r)=\int_{\partial B_{r}} u^{2} \frac{\left\langle A \nabla_{H^{n}} d, \nabla_{H^{n}} d\right\rangle}{|\nabla d|} \mathrm{d} H^{2 n}
$$

We also let

$$
\begin{aligned}
D(r) & =\int_{B_{r}}\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle \mathrm{d} z \mathrm{~d} t \\
I(r) & =\int_{B_{r}}\left(\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle+V u^{2}\right) \mathrm{d} z \mathrm{~d} t
\end{aligned}
$$

and call these quantities the Dirichlet integral and the total energy of $u$ in $B_{r}$, respectively.

Remark 3.1 In view of the elliptic assumption (1.8) and the fact $\left|\nabla_{H^{n}} d\right|^{2}=\psi$, there exist constants $C_{1}$ and $C_{2}$, such that

$$
\begin{gather*}
C_{1} \int_{\partial B_{r}} u^{2} \frac{\psi}{|\nabla d|} \mathrm{d} H^{2 n} \leq H(r) \leq C_{2} \int_{\partial B_{r}} u^{2} \frac{\psi}{|\nabla d|} \mathrm{d} H^{2 n}  \tag{3.1}\\
C_{1} \int_{B_{r}}\left|\nabla_{H^{n}} u\right|^{2} \mathrm{~d} z \mathrm{~d} t \leq D(r) \leq C_{2} \int_{B_{r}}\left|\nabla_{H^{n}} u\right|^{2} \mathrm{~d} z \mathrm{~d} t \tag{3.2}
\end{gather*}
$$

Lemma 3.1 Let $u$ be a weak solution of (1.7) in $B_{R_{0}}$. Then there exists an $r_{0}>0$ depending only on $Q, M$ and $f$ in (1.11), such that either $u \equiv 0$ in $B_{r_{0}}$ or $H(r) \neq 0$ for every $r \in\left(0, r_{0}\right)$.

Proof Suppose that for some $r_{0}<R_{0}, H\left(r_{0}\right)=0$. Then $u=0$ a.e. on $\partial B_{r_{0}}$. Therefore, from (2.2), the divergence theorem and the outer unit normal on $\partial B_{r}$ being $\vec{n}=|\nabla d|^{-1} \nabla d$, we have

$$
\begin{align*}
D\left(r_{0}\right) & =I\left(r_{0}\right)-\int_{B_{r_{0}}} V(z, t) u^{2}(z, t) \mathrm{d} z \mathrm{~d} t \\
& \leq \frac{1}{2} \int_{B_{r_{0}}} \mathcal{L}\left(u^{2}\right) \mathrm{d} z \mathrm{~d} t+\int_{B_{r_{0}}}|V(z, t)| u^{2}(z, t) \mathrm{d} z \mathrm{~d} t \\
& =\frac{1}{2} \int_{B_{r_{0}}} \operatorname{div}\left(S^{T} A \nabla_{H^{n}} u^{2}\right) \mathrm{d} z \mathrm{~d} t+\int_{B_{r_{0}}}|V(z, t)| u^{2}(z, t) \mathrm{d} z \mathrm{~d} t \\
& =\int_{\partial B_{r_{0}}} u \frac{\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} d\right\rangle}{|\nabla d|} \mathrm{d} H^{2 n}+\int_{B_{r_{0}}}|V(z, t)| u^{2}(z, t) \mathrm{d} z \mathrm{~d} t \\
& =\int_{B_{r_{0}}}|V(z, t)| u^{2}(z, t) \mathrm{d} z \mathrm{~d} t \tag{3.3}
\end{align*}
$$

Now we use the assumption of $V(1.11)$ and (2.7) of Lemma 2.1 to get the bound

$$
\begin{align*}
& \int_{B_{r_{0}}}|V(z, t)| u^{2}(z, t) \mathrm{d} z \mathrm{~d} t \\
\leq & M f\left(r_{0}\right) \int_{B_{r_{0}}} \frac{\psi}{d^{2}} u^{2} \mathrm{~d} z \mathrm{~d} t \\
\leq & \left(\frac{2}{Q-2}\right)^{2}\left\{\left(\frac{Q-2}{2}\right) \frac{1}{r_{0}} \int_{\partial B_{r_{0}}} u^{2} \frac{\psi}{|\nabla d|^{2}} \mathrm{~d} H^{2 n}+\int_{B_{r_{0}}}\left|\nabla_{H^{n}} u\right|^{2} \mathrm{~d} z \mathrm{~d} t\right\} \\
\leq & C f\left(r_{0}\right) D\left(r_{0}\right) \tag{3.4}
\end{align*}
$$

Since by (1.10) $\lim _{r \rightarrow 0^{+}} f(r)=0$, we obtain a contradiction from (3.3)-(3.4) unless $D\left(r_{0}\right)=0$, which implies that $u \equiv 0$ in $B_{r_{0}}$. This completes the proof of the lemma.

Lemma 3.1 allows us to introduce the Almgren's generalized frequency of $u$ on $B_{r}$ as following:

$$
N(r)= \begin{cases}\frac{r I(r)}{H(r)}, & \text { if } H \neq 0 \\ 0, & \text { if } H=0\end{cases}
$$

Lemma 3.1 also implies that $r \rightarrow N(r)$ is absolutely continuous on $\left(0, r_{0}\right)$. Therefore, if we set

$$
\begin{equation*}
\Omega_{r_{0}}=\left\{r \in\left(0, r_{0}\right) \mid N(r)>\max \left\{1, N\left(r_{0}\right)\right\}\right\} \tag{3.5}
\end{equation*}
$$

then $\Omega_{r_{0}}$ is an open subset of $\mathbb{R}$. Hence there holds a decomposition

$$
\begin{equation*}
\Omega_{r_{0}}=\bigcup_{j=1}^{\infty}\left(a_{j}, b_{j}\right) \quad \text { with } a_{j}, b_{j} \notin \Omega_{r_{0}} \tag{3.6}
\end{equation*}
$$

Obviously in $\Omega_{r_{0}}$, we have $N(r)>1$, i.e.,

$$
\begin{equation*}
\frac{H(r)}{r}<I(r) \quad \text { for every } r \in \Omega_{r_{0}} \tag{3.7}
\end{equation*}
$$

Lemma 3.2 There exists a constant $C=C(Q, M, f)>0$, such that for every $r \in \Omega_{r_{0}}$, we have

$$
\begin{equation*}
D(r) \leq C I(r) \tag{3.8}
\end{equation*}
$$

Proof As in the proof of (3.4), we have

$$
\begin{aligned}
D(r) & \leq I(r)+\int_{B_{r}}|V(z, t)| u(z, t)^{2} \mathrm{~d} z \mathrm{~d} t \\
& \leq I(r)+\left(\frac{2}{Q-2}\right)^{2} M f(r)\left\{\left(\frac{Q-2}{2}\right) \frac{H(r)}{r}+D(r)\right\} \\
& \leq\left[1+\frac{2}{Q-2} M f(r)\right] I(r)+\left(\frac{2}{Q-2}\right)^{2} M f(r) D(r)
\end{aligned}
$$

where in the last inequality we have used (3.7). We can choose small $r_{0}>0$ such that $\left(\frac{2}{Q-2}\right)^{2} M f\left(r_{0}\right)<1$, and thus we prove $D(r) \leq C I(r)$.

Proposition 3.1 For a.e. $r \in\left(0, R_{0}\right)$, the total energy of $u$ on $B_{r}$ can be expressed by the surface integral

$$
\begin{equation*}
I(r)=\int_{\partial B_{r}} u \frac{\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} d\right\rangle}{|\nabla d|} \mathrm{d} H^{2 n} \tag{3.9}
\end{equation*}
$$

Proof By using the divergence theorem, (2.2) and the fact $\mathcal{L} u=V u$,

$$
\begin{aligned}
& \int_{\partial B_{r}} u \frac{\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} d\right\rangle}{|\nabla d|} \mathrm{d} H^{2 n} \\
= & \int_{\partial B_{r}} u\left\langle S^{\mathrm{T}} A \nabla_{H^{n}} u, \vec{n}\right\rangle \mathrm{d} H^{2 n} \\
= & \int_{B_{r}} \operatorname{div}\left(u S^{\mathrm{T}} A \nabla_{H^{n}} u\right) \mathrm{d} z \mathrm{~d} t \\
= & \int_{B_{r}} u \operatorname{div}\left(S^{\mathrm{T}} A \nabla_{H^{n}} u\right) \mathrm{d} z \mathrm{~d} t+\int_{B_{r}} \nabla u S^{\mathrm{T}} A \nabla_{H^{n}} u \mathrm{~d} z \mathrm{~d} t \\
= & \int_{B_{r}} V u^{2} \mathrm{~d} z \mathrm{~d} t+\int_{B_{r}}\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle \mathrm{d} z \mathrm{~d} t=I(r) .
\end{aligned}
$$

This completes the proof of the proposition.
By the definition of $N(r)$, we get

$$
\begin{equation*}
\frac{N^{\prime}(r)}{N(r)}=\frac{1}{r}+\frac{I^{\prime}(r)}{I(r)}-\frac{H^{\prime}(r)}{H(r)} \tag{3.10}
\end{equation*}
$$

Next, we compute $H^{\prime}(r)$ and $I^{\prime}(r)$ respectively by using the conditions (1.8)-(1.9) on the coefficients $\left(a_{i j}\right)$ and some estimates given in Section 2.

Theorem 3.1 There exists a positive constant $C_{1}=C_{1}(\lambda, \Lambda)$, such that for a.e. $r \in\left(0, R_{0}\right)$, one has

$$
\begin{equation*}
\left|H^{\prime}(r)-\frac{Q-1}{r} H(r)-2 I(r)\right| \leq C_{1} H(r) \tag{3.11}
\end{equation*}
$$

Proof The divergence theorem gives

$$
\begin{aligned}
H(r) & =\int_{\partial B_{r}} u^{2} \frac{\left\langle A \nabla_{H^{n}} d, \nabla_{H^{n}} d\right\rangle}{|\nabla d|} \mathrm{d} H^{2 n} \\
& =\int_{\partial B_{r}} u^{2}\left\langle S^{\mathrm{T}} A \nabla_{H^{n}} d, \vec{n}\right\rangle \mathrm{d} H^{2 n} \\
& =\int_{B_{r}} \operatorname{div}\left(u^{2} S^{\mathrm{T}} A \nabla_{H^{n}} d\right) \mathrm{d} z \mathrm{~d} t \\
& =\int_{B_{r}} u^{2} \operatorname{div}\left(S^{\mathrm{T}} A \nabla_{H^{n}} d\right) \mathrm{d} z \mathrm{~d} t+\int_{B_{r}}\left\langle S^{\mathrm{T}} A \nabla_{H^{n}} d, \nabla u^{2}\right\rangle \mathrm{d} z \mathrm{~d} t \\
& =\int_{B_{r}} u^{2} \mathcal{L} d \mathrm{~d} z \mathrm{~d} t+\int_{B_{r}} 2 u\left\langle A \nabla_{H^{n}} d, \nabla_{H^{n}} u\right\rangle \mathrm{d} z \mathrm{~d} t
\end{aligned}
$$

We now recall Federer's co-area formula (see [6]): Let $f \in L^{1}\left(\mathbb{R}^{N}\right)$ and $g \in \operatorname{Lip}\left(\mathbb{R}^{N}\right)$. Then

$$
\begin{equation*}
\int_{\mathbb{R}^{N}} f(x) \mathrm{d} x=\int_{-\infty}^{+\infty} \mathrm{d} s \int_{\{g=s\}} \frac{f(x)}{|\nabla g(x)|} \mathrm{d} H^{N-1} \tag{3.12}
\end{equation*}
$$

provided that $\nabla g$ does not vanish on the set $\{g=s\}$ for a.e. $s \in \mathbb{R}$.
Using (3.12) and Proposition 3.1, and differentiating $H(r)$ with respect to $r$, we obtain

$$
\begin{aligned}
H^{\prime}(r) & =\int_{\partial B_{r}} \frac{u^{2} \mathcal{L} d}{|\nabla d|} \mathrm{d} H^{2 n}+\int_{\partial B_{r}} \frac{2 u\left\langle A \nabla_{H^{n}} d, \nabla_{H^{n}} u\right\rangle}{|\nabla d|} \mathrm{d} H^{2 n} \\
& =2 I(r)+\int_{\partial B_{r}} \frac{u^{2} \mathcal{L} d}{|\nabla d|} \mathrm{d} H^{2 n}
\end{aligned}
$$

This implies

$$
\begin{aligned}
& H^{\prime}(r)-\frac{Q-1}{r} H(r)-2 I(r) \\
= & \int_{\partial B_{r}} \frac{u^{2} \mathcal{L} d}{|\nabla d|} \mathrm{d} H^{2 n}-\frac{Q-1}{r} \int_{\partial B_{r}} u^{2} \frac{\left\langle A \nabla_{H^{n}} d, \nabla_{H^{n}} d\right\rangle}{|\nabla d|} \mathrm{d} H^{2 n} \\
= & \int_{\partial B_{r}} u^{2} \frac{\operatorname{div}\left(S^{\mathrm{T}} B \nabla_{H^{n}} d\right)}{|\nabla d|} \mathrm{d} H^{2 n}+\int_{\partial B_{r}} u^{2} \frac{\Delta_{H^{n}} d}{|\nabla d|} \mathrm{d} H^{2 n} \\
& -\frac{Q-1}{r} \int_{\partial B_{r}} u^{2} \frac{\left\langle B \nabla_{H^{n}} d, \nabla_{H^{n}} d\right\rangle}{|\nabla d|} \mathrm{d} H^{2 n}-\frac{Q-1}{r} \int_{\partial B_{r}} u^{2} \frac{\left|\nabla_{H^{n}} d\right|^{2}}{|\nabla d|} \mathrm{d} H^{2 n}
\end{aligned}
$$

Using the formula

$$
\Delta_{H^{n}} d=\frac{Q-1}{d}\left|\nabla_{H^{n}} d\right|^{2}
$$

we get

$$
\begin{aligned}
& H^{\prime}(r)-\frac{Q-1}{r} H(r)-2 I(r) \\
= & \int_{\partial B_{r}} u^{2} \frac{\operatorname{div}\left(S^{\mathrm{T}} B \nabla_{H^{n}} d\right)}{|\nabla d|} \mathrm{d} H^{2 n}-\frac{Q-1}{r} \int_{\partial B_{r}} u^{2} \frac{\left\langle B \nabla_{H^{n}} d, \nabla_{H^{n}} d\right\rangle}{|\nabla d|} \mathrm{d} H^{2 n} .
\end{aligned}
$$

We estimate the two terms on the right-hand side, which thanks to (1.8)-(1.9), yields

$$
\frac{\left\langle B \nabla_{H^{n}} d, \nabla_{H^{n}} d\right\rangle}{|\nabla d|} \leq C d \frac{\left\langle\nabla_{H^{n}} d, \nabla_{H^{n}} d\right\rangle}{|\nabla d|} \leq C d \frac{\left\langle A \nabla_{H^{n}} d, \nabla_{H^{n}} d\right\rangle}{|\nabla d|}
$$

and thus

$$
\left|\frac{Q-1}{r} \int_{\partial B_{r}} u^{2} \frac{\left\langle B \nabla_{H^{n}} d, \nabla_{H^{n}} d\right\rangle}{|\nabla d|} \mathrm{d} H^{2 n}\right| \leq C H(r)
$$

Finally, we estimate the first term on the right-hand side. Writing the divergence term as

$$
\operatorname{div}\left(S^{\mathrm{T}} B \nabla_{H^{n}} d\right)=X_{i}\left(b_{i j} X_{j} d\right)=\left(X_{i} b_{i j}\right) \cdot X_{j} d+b_{i j} \cdot\left(X_{i} X_{j} d\right)
$$

and taking into account the assumption (1.9) and Proposition 2.1, we get the following inequalities:

$$
\left|\left(X_{i} b_{i j}\right) X_{j} d\right| \leq\left|X_{i} b_{i j}\right| \cdot\left|X_{j} d\right| \leq C \psi^{\frac{1}{2}} \cdot \psi^{\frac{1}{2}} \leq C \psi
$$

and

$$
\left|b_{i j}\left(X_{i} X_{j} d\right)\right| \leq\left|b_{i j}\right| \cdot\left|X_{i} X_{j} d\right| \leq C \psi d \cdot \frac{1}{d} \leq C \psi
$$

Hence,

$$
\int_{\partial B_{r}} u^{2} \frac{\operatorname{div}\left(S^{\mathrm{T}} B \nabla_{H^{n}} d\right)}{|\nabla d|} \mathrm{d} H^{2 n} \leq C \int_{\partial B_{r}} u^{2} \frac{\psi}{|\nabla d|} \mathrm{d} H^{2 n} \leq C H(r)
$$

Therefore,

$$
\left|H^{\prime}(r)-\frac{Q-1}{r} H(r)-2 I(r)\right| \leq C_{1} H(r)
$$

Next, we need to estimate $I^{\prime}(r)$, letting

$$
\begin{equation*}
\mu=\left\langle A \nabla_{H^{n}} d, \nabla_{H^{n}} d\right\rangle, \quad \nu=\left\langle B \nabla_{H^{n}} d, \nabla_{H^{n}} d\right\rangle \tag{3.13}
\end{equation*}
$$

and note that $\lambda \psi \leq \mu \leq \Lambda \psi$, and moreover $\psi=\mu-\nu$.
Consider the vector field $F$ defined as follows:

$$
\begin{equation*}
F=\frac{d}{\mu} \sum_{i, j=1}^{2 n} a_{i j} X_{j} \mathrm{~d} X_{i} \tag{3.14}
\end{equation*}
$$

i.e.,

$$
\begin{equation*}
F u=\frac{d}{\mu}\left\langle A \nabla_{H^{n}} d, \nabla_{H^{n}} u\right\rangle \tag{3.15}
\end{equation*}
$$

Hence

$$
\begin{equation*}
F d=\langle F, \nabla d\rangle=d \tag{3.16}
\end{equation*}
$$

Lemma 3.3 (Rellich-Type Identity) Let $F$ be the above considered vector field in $H^{n}$. Then we have the following identity:

$$
\begin{aligned}
& \int_{\partial B_{r}}\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle\langle F, \vec{n}\rangle \mathrm{d} H^{2 n} \\
= & 2 \int_{\partial B_{r}} a_{j k} X_{j} u\left\langle X_{k}, \vec{n}\right\rangle F u \mathrm{~d} H^{2 n} \\
& -2 \int_{B_{r}} a_{j k} X_{j} u\left[X_{k}, F\right] u \mathrm{~d} z \mathrm{~d} t+\int_{B_{r}} \operatorname{div}(F)\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle \mathrm{d} z \mathrm{~d} t \\
& +\int_{B_{r}}\left\langle(F A) \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle \mathrm{d} z \mathrm{~d} t-2 \int_{B_{r}} F u \mathcal{L} u \mathrm{~d} z \mathrm{~d} t .
\end{aligned}
$$

Proof The divergence theorem yields

$$
\begin{aligned}
& \int_{\partial B_{r}}\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle\langle F, \vec{n}\rangle \mathrm{d} H^{2 n} \\
= & \int_{B_{r}} \operatorname{div}\left(F\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle\right) \mathrm{d} z \mathrm{~d} t \\
= & \int_{B_{r}}(\operatorname{div} F)\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle \mathrm{d} z \mathrm{~d} t+\int_{B_{r}}\left\langle(F A) \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle \mathrm{d} z \mathrm{~d} t \\
& +2 \int_{B_{r}}\left\langle A \nabla_{H^{n}} u, F \nabla_{H^{n}} u\right\rangle \mathrm{d} z \mathrm{~d} t .
\end{aligned}
$$

On the other hand,

$$
\begin{aligned}
& 2 \int_{\partial B_{r}} a_{j k} X_{j} u\left\langle X_{k}, \vec{n}\right\rangle F u \mathrm{~d} H^{2 n} \\
= & 2 \int_{B_{r}} \operatorname{div}\left(a_{j k} X_{j} u F u X_{k}\right) \mathrm{d} z \mathrm{~d} t \\
= & 2 \int_{B_{r}} \operatorname{div}\left(X_{k}\right) a_{j k} X_{j} u F u \mathrm{~d} z \mathrm{~d} t+2 \int_{B_{r}} X_{k}\left(a_{j k} X_{j} u\right) F u \mathrm{~d} z \mathrm{~d} t+2 \int_{B_{r}} a_{j k} X_{j} u\left(X_{k} F u\right) \mathrm{d} z \mathrm{~d} t .
\end{aligned}
$$

In view of the fact $\operatorname{div}\left(X_{k}\right)=0$, and the identities

$$
X_{k} F u-F X_{k} u=\left[X_{k}, F\right] u \quad \text { for any } k
$$

we obtain

$$
\begin{aligned}
& \int_{\partial B_{r}}\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle\langle F, \vec{n}\rangle \mathrm{d} H^{2 n} \\
= & 2 \int_{\partial B_{r}} a_{j k} X_{j} u\left\langle X_{k}, \vec{n}\right\rangle F u \mathrm{~d} H^{2 n}-2 \int_{B_{r}} a_{j k} X_{j} u\left[X_{k}, F\right] u \mathrm{~d} z \mathrm{~d} t \\
& +\int_{B_{r}} \operatorname{div}(F)\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle \mathrm{d} z \mathrm{~d} t+\int_{B_{r}}\left\langle(F A) \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle \mathrm{d} z \mathrm{~d} t \\
& -2 \int_{B_{r}} F u \mathcal{L} u \mathrm{~d} z \mathrm{~d} t .
\end{aligned}
$$

This completes the proof of Lemma 3.3.

Theorem 3.2 Let $u$ be a polyradial solution to (1.7), then there exist positive constants $C_{2}=C_{2}(\lambda, \Lambda)$ and $C_{3}=C_{3}(\lambda, \Lambda)$, such that for a.e. $r \in \Omega_{r_{0}}$, we have

$$
\begin{equation*}
I^{\prime}(r) \geq 2 \int_{\partial B_{r}} \frac{1}{\mu} \frac{\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} d\right\rangle^{2}}{|\nabla d|} \mathrm{d} H_{2}-C_{2} \frac{f(r)}{r} I(r)-C_{3} I(r) \tag{3.17}
\end{equation*}
$$

where $\mu$ is defined in (3.13).
Remark 3.2 On $H^{1}$, a polyradial function $u$ is equivalent to $\widetilde{T} u=\left(y_{i} \frac{\partial u}{\partial x_{i}}-x_{i} \frac{\partial u}{\partial y_{i}}\right)=0$. On $H^{n}(n>1)$, a polyradial function $u$ implies that $\widetilde{T} u=0$, however, the converse is false. For example, for $\left(x_{1}, x_{2}, y_{1}, y_{2}, t\right) \in H^{2}$, take $u=x_{1} x_{2}+y_{1} y_{2}+t$. A direct calculation yields $\widetilde{T} u=0$, but $u$ is not a polyradial function. However, over the course of our proof of Theorem 3.2 , we only need the condition $\widetilde{T} u=0$. Thus we have the following more general result.

Corollary 3.1 Let u be a solution to (1.7) satisfying $\widetilde{T} u=0$. Then Theorem 3.2 also holds.
Proof of Theorem 3.2 By using the co-area formula (3.12),

$$
I(r)=\int_{0}^{r} \int_{\partial B_{\rho}} \frac{\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle}{|\nabla d|} \mathrm{d} H^{2 n} \mathrm{~d} \rho+\int_{0}^{r} \int_{\partial B_{\rho}} \frac{V u^{2}}{|\nabla d|} \mathrm{d} H^{2 n} \mathrm{~d} \rho .
$$

Differentiating $I(r)$ with respect to $r$, we get

$$
I^{\prime}(r)=\int_{\partial B_{r}} \frac{\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle}{|\nabla d|} \mathrm{d} H^{2 n}+\int_{\partial B_{r}} \frac{V u^{2}}{|\nabla d|} \mathrm{d} H^{2 n} .
$$

From (3.16), $\mathcal{L} u=V u$ and Rellich-type identity Lemma 3.3, we obtain

$$
\begin{align*}
I^{\prime}(r)= & \frac{1}{r} \int_{\partial B_{r}}\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle\left\langle F, \frac{\nabla d}{|\nabla d|}\right\rangle \mathrm{d} H^{2 n}+\int_{\partial B_{r}} \frac{V u^{2}}{|\nabla d|} \mathrm{d} H^{2 n} \\
= & \frac{2}{r} \int_{\partial B_{r}} a_{j k} X_{j} u\left\langle X_{k}, \vec{n}\right\rangle F u \mathrm{~d} H^{2 n}-\frac{2}{r} \int_{B_{r}} a_{j k} X_{j} u\left[X_{k}, F\right] u \mathrm{~d} z \mathrm{~d} t \\
& +\frac{1}{r} \int_{B_{r}} \operatorname{div}(F)\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle \mathrm{d} z \mathrm{~d} t+\frac{1}{r} \int_{B_{r}}\left\langle(F A) \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle \mathrm{d} z \mathrm{~d} t \\
& -\frac{2}{r} \int_{B_{r}} F u V u \mathrm{~d} z \mathrm{~d} t+\int_{\partial B_{r}} \frac{V u^{2}}{|\nabla d|} \mathrm{d} H^{2 n} \\
= & \mathrm{I}_{1}+\mathrm{I}_{2}+\mathrm{I}_{3}+\mathrm{I}_{4}+\mathrm{I}_{5}+\mathrm{I}_{6} . \tag{3.18}
\end{align*}
$$

First, by using the definition of $F$, we deal with $\mathrm{I}_{1}$ as follows:

$$
\begin{align*}
\mathrm{I}_{1} & =\frac{2}{r} \int_{\partial B_{r}} a_{j k} X_{j} u\left\langle X_{k}, \vec{n}\right\rangle F u \mathrm{~d} H^{2 n} \\
& =\frac{2}{r} \int_{\partial B_{r}} a_{j k} X_{j} u \frac{X_{k} d}{|\nabla d|} \cdot \frac{d}{\mu}\left\langle A \nabla_{H^{n}} d, \nabla_{H^{n}} u\right\rangle \mathrm{d} H^{2 n} \\
& =2 \int_{\partial B_{r}} \frac{1}{\mu} \cdot \frac{\left\langle A \nabla_{H^{n}} d, \nabla_{H^{n}} u\right\rangle^{2}}{|\nabla d|} \mathrm{d} H^{2 n} \tag{3.19}
\end{align*}
$$

Now we use (1.11), (3.1) and (3.7) to get the bound of $\mathrm{I}_{6}$ as follows:

$$
\begin{align*}
\left|\mathrm{I}_{6}\right| & \leq \int_{\partial B_{r}} \frac{|V| u^{2}}{|\nabla d|} \mathrm{d} H^{2 n} \\
& \leq C \frac{f(r)}{r^{2}} \int_{\partial B_{r}} u^{2} \frac{\psi}{|\nabla d|} \mathrm{d} H^{2 n} \leq C \frac{f(r)}{r} \frac{H(r)}{r} \leq \frac{f(r)}{r} I(r) \tag{3.20}
\end{align*}
$$

By using conditions (1.9) and (3.13), we estimate $|F u|$ as follows:

$$
\begin{aligned}
|F u| & =\frac{d}{\mu} a_{i j} X_{i} d X_{j} u=\frac{d}{\mu} b_{i j} X_{i} d X_{j} u+\frac{d}{\mu} X_{i} d X_{i} u \\
& \leq \frac{d}{\mu}\left|b_{i j}\right|\left|X_{i} d\right|\left|X_{j} u\right|+\frac{d}{\mu}\left|X_{i} d\right|\left|X_{i} u\right| \\
& \leq C d \psi^{-\frac{1}{2}}|X u|
\end{aligned}
$$

With the help of (1.11) and (2.7), we can estimate $I_{5}$ as follows:

$$
\begin{align*}
\left|\mathrm{I}_{5}\right| & \leq \frac{2}{r} \int_{B_{r}}|F u||V(z, t)||u(z, t)| \mathrm{d} z \mathrm{~d} t \\
& \leq C \frac{f(r)}{r} \int_{B_{r}} \frac{\psi^{\frac{1}{2}}|u|}{d}|X u| \mathrm{d} z \mathrm{~d} t \\
& \leq C \frac{f(r)}{r} \int_{B_{r}} \frac{u^{2} \psi}{d^{2}} \mathrm{~d} z \mathrm{~d} t+C \frac{f(r)}{r} \int_{B_{r}}\left|\nabla_{H^{n}} u\right|^{2} \mathrm{~d} z \mathrm{~d} t \\
& \leq C f(r) \frac{H(r)}{r}+C \frac{f(r)}{r} D(r) \leq C \frac{f(r)}{r} I(r) \tag{3.21}
\end{align*}
$$

Next we get a bound for $\mathrm{I}_{4}$ : For every $r, s=1, \cdots, 2 n$, we have

$$
\begin{aligned}
\left|F a_{r s}\right| & =\left|\frac{d}{\mu} a_{i j} X_{i} d X_{j}\left(a_{r s}\right)\right| \\
& \leq\left|\frac{d}{\mu} b_{i j} X_{i} d X_{j}\left(a_{r s}\right)\right|+\left|\frac{d}{\mu} X_{i} d X_{i} b_{r s}\right| \\
& \leq \frac{d}{\mu}\left|b_{i j}\right|\left|X_{i} d\right|\left|X_{j}\left(a_{r s}\right)\right|+\frac{d}{\mu}\left|X_{i} d\right|\left|X_{i} b_{r s}\right| \\
& \leq \frac{d}{\mu} d \psi \psi^{\frac{1}{2}} \psi^{\frac{1}{2}}+\frac{d}{\mu} \psi^{\frac{1}{2}} \psi^{\frac{1}{2}} \leq C d .
\end{aligned}
$$

Hence

$$
\begin{align*}
\left|\mathrm{I}_{4}\right| & \leq \frac{1}{r} \int_{B_{r}}\left|\left\langle(F A) \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle\right| \mathrm{d} z \mathrm{~d} t \\
& \leq C \frac{1}{r} \int_{B_{r}} d\left\langle\nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle \mathrm{d} z \mathrm{~d} t \\
& \leq C D(r) \leq C I(r) \tag{3.22}
\end{align*}
$$

We now would like to get a bound for $\mathrm{I}_{3}$ : Because of $\operatorname{div}\left(X_{i}\right)=0$ for every $i=1, \cdots, 2 n$, we get

$$
\begin{aligned}
\operatorname{div} F= & \operatorname{div}\left(\frac{d}{\mu} a_{i j} X_{j} d X_{i}\right)=\frac{d}{\mu} a_{i j} X_{j} d\left(\operatorname{div} X_{i}\right)+X_{i}\left(\frac{d}{\mu} a_{i j} X_{j} d\right)=X_{i}\left(\frac{d}{\mu}\left(a_{i j}\right) X_{j} d\right) \\
= & \frac{1}{\mu} X_{i} d\left(a_{i j}\right) X_{j} d-\frac{d}{\mu^{2}} X_{i} \mu a_{i j} X_{j} d+\frac{d}{\mu}\left(X_{i} a_{i j}\right) X_{j} d+\frac{d}{\mu} a_{i j}\left(X_{i} X_{j} d\right) \\
= & \frac{1}{\mu} X_{i} d\left(b_{i j}\right) X_{j} d+\frac{1}{\mu} X_{i} d X_{i} d-\frac{d}{\mu^{2}} X_{i} \mu\left(b_{i j}\right) X_{j} d-\frac{d}{\mu^{2}} X_{i} \mu X_{i} d \\
& +\frac{d}{\mu}\left(X_{i} a_{i j}\right) X_{j} d+\frac{d}{\mu} b_{i j}\left(X_{i} X_{j} d\right)+\frac{d}{\mu}\left(X_{i} X_{i} d\right) .
\end{aligned}
$$

Here

$$
\begin{aligned}
X_{i} \mu & =X_{i}\left\langle A \nabla_{H^{n}} d, \nabla_{H^{n}} d\right\rangle \\
& =X_{i}\left(a_{k l} X_{k} d X_{l} d\right) \\
& =X_{i}\left(a_{k l}\right) X_{k} d X_{l} d+2 a_{k l}\left(X_{i} X_{k} d\right) X_{l} d \\
& =X_{i}\left(a_{k l}\right) X_{k} d X_{l} d+2 b_{k l}\left(X_{i} X_{k} d\right) X_{l} d+2\left(X_{i} X_{k} d\right) X_{k} d,
\end{aligned}
$$

and then

$$
\begin{equation*}
\left|X_{i} \mu\right| \leq C \frac{1}{d} \psi^{\frac{1}{2}} \tag{3.23}
\end{equation*}
$$

According to $X_{i} d\left(X_{i} X_{k} d\right) X_{k} d=0$, we have

$$
\begin{aligned}
& \left|\frac{d}{\mu^{2}} X_{i} \mu\left(a_{i j}\right) X_{j} d+\frac{d}{\mu^{2}} X_{i} \mu X_{i} d\right| \\
= & \frac{d}{\mu^{2}}\left\{X_{i}\left(a_{k l}\right) X_{k} d X_{l} d\left(b_{i j}\right) X_{j} d+2 b_{k l}\left(X_{i} X_{k} d\right) X_{l} d\left(b_{i j}\right) X_{j} d+2\left(X_{i} X_{k} d\right) X_{k} d\left(b_{i j}\right) X_{j} d\right. \\
& \left.+\left(X_{i} a_{k l}\right) X_{k} d X_{l} d X_{i} d+2 b_{k l}\left(X_{i} X_{k} d\right) X_{l} d X_{i} d+2\left(X_{i} X_{k} d\right) X_{k} d X_{i} d\right\} \\
\leq & C \frac{d}{\mu^{2}} \psi^{2} \leq C d .
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
|\operatorname{div} F| & \leq \frac{1}{\mu}\left(b_{i j} X_{j} d X_{i} d+\left(X_{i} d\right)^{2}\right)+\frac{d}{\mu}\left(X_{i} b_{i j} X_{j} d+b_{i j} X_{i} X_{j} d+X_{i} X_{i} d\right)+C d \\
& \leq C
\end{aligned}
$$

and thus

$$
\begin{align*}
\left|\mathrm{I}_{3}\right| & \leq C \frac{1}{r} \int_{B_{r}}\left\langle A \nabla_{H^{n}} u, \nabla_{H^{n}} u\right\rangle \mathrm{d} z \mathrm{~d} t \\
& \leq C \frac{1}{r} D(r) \leq C \frac{1}{r} I(r) . \tag{3.24}
\end{align*}
$$

Finally, under the assumption $\widetilde{T} u=0$, we get (2.4). Let us estimate $\mathrm{I}_{2}$ as follows:

$$
\begin{aligned}
F u & =\frac{d}{\mu} a_{i j} X_{i} d X_{j} u=\frac{d}{\mu} b_{i j} X_{i} d X_{j} u+\frac{d}{\mu} X_{i} d X_{i} u \\
& =\frac{d}{\mu} b_{i j} X_{i} d X_{j} u+\frac{d}{\mu}\left(\frac{1}{d} \psi Z u\right)=\frac{d}{\mu} b_{i j} X_{i} d X_{j} u+\frac{\psi}{\mu} Z u \\
& =\frac{d}{\mu} b_{i j} X_{i} d X_{j} u+Z u-\frac{\nu}{\mu} Z u .
\end{aligned}
$$

Hence

$$
\begin{equation*}
\left[X_{k}, F\right] u=\left[X_{k}, \frac{d}{\mu} b_{i j} X_{i} d X_{j}\right] u+\left[X_{k}, Z\right] u-\left[X_{k}, \frac{\nu}{\mu} Z\right] u \tag{3.25}
\end{equation*}
$$

We estimate the first term of (3.25) as follows:

$$
\begin{aligned}
& \left|\left[X_{k}, \frac{d}{\mu} b_{i j} X_{i} d X_{j}\right] u\right| \\
\leq & \left|X_{k}\left(\frac{d}{\mu} b_{i j} X_{i} d\right) X_{j} u\right|+\left|\frac{d}{\mu} b_{i j} X_{i} d\left[X_{k}, X_{j}\right] u\right| \\
\leq & \left|\frac{1}{\mu} X_{k} d b_{i j} X_{i} d X_{j} u\right|+\left|\frac{d}{\mu^{2}} X_{k} \mu b_{i j} X_{i} d X_{j} u\right|+\left|\frac{d}{\mu} X_{k} b_{i j} X_{i} d X_{j} u\right| \\
& +\left|\frac{d}{\mu} b_{i j}\left(X_{k} X_{I} d\right) X_{j} u\right|+\left|\frac{d}{\mu} b_{i j} X_{i} d\left[X_{k}, X_{j}\right] u\right| \\
\leq & C d|X u|+\left|\frac{d}{\mu} b_{i j} X_{i} d\left[X_{k}, X_{j}\right] u\right| \\
\leq & C d|X u|+\frac{d}{\mu}\left|b_{i j}\right|\left|X_{i} d\right| \frac{1}{|z|}|X u| \\
\leq & C d|X u| .
\end{aligned}
$$

Because of (2.4) and $\left|X_{k} \nu\right|=X_{k}\left(b_{r s} X_{r} d X_{s} d\right) \leq C \psi^{\frac{3}{2}}$, the last term of (3.25) is

$$
\begin{aligned}
\left|\left[X_{k}, \frac{\nu}{\mu} Z\right] u\right| & =\left|\left[X_{k}, \frac{\nu}{\mu} \cdot \frac{d}{\psi} X_{i} d X_{i}\right] u\right| \\
& \leq\left|X_{k}\left(\frac{\nu}{\mu} \cdot \frac{d}{\psi} X_{i} d\right)\right|\left|X_{i} u\right|+\left|\frac{\nu}{\mu} \cdot \frac{d}{\psi} X_{i} d\left[X_{k}, X_{i}\right] u\right| \\
& \leq C|X u|
\end{aligned}
$$

Therefore,

$$
\begin{equation*}
\mathrm{I}_{2} \leq C \frac{1}{r} \int_{B_{r}}\left|\nabla_{H^{n}} u\right|^{2} \mathrm{~d} z \mathrm{~d} t \leq C \frac{1}{r} I(r) \tag{3.26}
\end{equation*}
$$

Substituting (3.19)-(3.22), (3.24) and (3.26) in (3.18), we obtain

$$
I^{\prime}(r) \geq 2 \int_{\partial B_{r}} \frac{1}{\mu} \cdot \frac{\left\langle A \nabla_{H^{n}} d, \nabla_{H^{n}} u\right\rangle^{2}}{|\nabla d|} \mathrm{d} H^{2 n}-C_{2} \frac{f(r)}{r} I(r)-C_{3} \frac{1}{r} I(r) .
$$

With the help of (3.10), Theorems 3.1 and 3.2 , we get the monotonicity of the frequency function.

Theorem 3.3 Let $u$ be a polyradial solution to (1.7). Then there exist positive constants $r_{0}=r_{0}(\lambda, \Lambda)$ and $C=C(\lambda, \Lambda)$, such that for a.e. $r \in \Omega_{r_{0}}$ we have

$$
\begin{equation*}
\frac{N^{\prime}(r)}{N(r)} \geq-C_{4} \frac{f(r)}{r}-C_{5} \frac{1}{r} . \tag{3.27}
\end{equation*}
$$

Proof Applying (3.11) and (3.17) in (3.10), we obtain

$$
\begin{aligned}
\frac{N^{\prime}(r)}{N(r)} \geq & \frac{1}{r}+\frac{2 \int_{\partial B_{r}} \frac{1}{\mu} \cdot \frac{\left\langle A \nabla_{\left.H^{n} d, \nabla_{H^{n}} u\right\rangle^{2}} \mathrm{~d} H^{2 n}\right.}{I(r d \mid}-C_{2} \frac{f(r)}{r}-C_{3} \frac{1}{r}}{} \\
& -\frac{Q-1}{r}-C_{1}-2 \frac{I(r)}{H(r)} \\
\geq & -C_{4} \frac{f(r)}{r}-C_{5} \frac{1}{r},
\end{aligned}
$$

where we have applied Proposition 3.1 and the Cauchy-Schwarz inequality.
By using the monotonicity of $N(r)$, it is easy to prove Theorems 1.1-1.2, and we give the proof in the current setting for completeness.

Proof of Theorem 1.1 We rewrite inequality (3.11) as

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t}\left(\ln \left(\frac{H(t)}{t^{Q-1}}\right)\right) \leq C_{1}+2 \frac{N(t)}{t}, \quad t \in\left(0, r_{0}\right) . \tag{3.28}
\end{equation*}
$$

Integrating (3.28) between $r$ and $2 r$, with $2 r<r_{0}$, we have

$$
\begin{align*}
\ln \left(\frac{H(2 r)}{H(r)} 2^{1-Q}\right) & \leq C_{1} r+2 \int_{r}^{2 r} N(t) \frac{1}{t} \mathrm{~d} t \\
& \leq C_{1} r+2 \int_{(r, 2 r) \cap \Omega_{r_{0}}} N(t) \frac{1}{t} \mathrm{~d} t+2 \int_{J_{r}} N(t) \frac{1}{t} \mathrm{~d} t, \tag{3.29}
\end{align*}
$$

where $J_{r}=\left\{t \in(r, 2 r) \mid t \notin \Omega_{r_{0}}, N(t) \geq 0\right\}$. Due to (3.5), on $J_{r}$ we have $0 \leq N(t) \leq$ $\max \left(1, N\left(r_{0}\right)\right)$,

$$
\begin{equation*}
\int_{J_{r}} N(t) \frac{1}{t} \mathrm{~d} t \leq \max \left(1, N\left(r_{0}\right)\right) \int_{r}^{2 r} \frac{1}{t} \mathrm{~d} t=\max \left(1, N\left(r_{0}\right)\right) \ln 2 . \tag{3.30}
\end{equation*}
$$

On the other hand, by using the monotonicity of $N(r)$, i.e., (3.27), we have

$$
\ln \frac{N\left(b_{j}\right)}{N(r)}=\int_{r}^{b_{j}} \frac{N^{\prime}(t)}{N(t)} \mathrm{d} t \geq-C_{4} \int_{0}^{r_{0}} \frac{f(t)}{t} \mathrm{~d} t-C_{5} \int_{r}^{r_{0}} \frac{1}{t} \mathrm{~d} t .
$$

From the above inequality, recalling that $b_{j} \notin \Omega_{r_{0}}$, we have

$$
N(r) \leq \exp \left(C_{4} \int_{0}^{R_{0}} \frac{f(t)}{t} \mathrm{~d} t+C_{5} \ln \frac{r_{0}}{r}\right) \max \left(1, N\left(r_{0}\right)\right) \quad \text { for every } r \in \Omega_{r_{0}} .
$$

Hence

$$
\begin{equation*}
\int_{(r, 2 r) \cap \Omega_{r_{0}}} N(t) \frac{1}{t} \mathrm{~d} t \leq \exp \left(C_{4} \int_{0}^{R_{0}} \frac{f(t)}{t} \mathrm{~d} t+C_{5} \ln \frac{r_{0}}{r}\right) \max \left(1, N\left(r_{0}\right)\right) \ln 2 . \tag{3.31}
\end{equation*}
$$

Applying (3.30)-(3.31) in (3.29), we finally obtain

$$
H(2 r) \leq \Gamma H(r) .
$$

Integrating with respect to $r$ and using the co-area formula we finally prove (1.12).
Proof of Theorem 1.2 Letting $r_{0}$ be as in Theorem 1.1, we obtain after $k$ interactions of (1.12)

$$
\begin{align*}
\int_{B_{r_{0}}} u^{2} \psi(z, t) \mathrm{d} z \mathrm{~d} t \leq \cdots & \leq \Gamma^{k} \int_{B_{2}-k_{r_{0}}} u^{2} \psi(z, t) \mathrm{d} z \mathrm{~d} t  \tag{3.32}\\
& =\Gamma^{k}\left|B_{2-k r_{0}}\right|^{\beta} \frac{1}{\left|B_{2-k} k_{0}\right|^{\beta}} \int_{B_{2-k_{0}}} u^{2} \psi(z, t) \mathrm{d} z \mathrm{~d} t \tag{3.33}
\end{align*}
$$

where $\beta>0$ is a number to be suitably chosen later. By (1.6), we have

$$
\Gamma^{k}\left|B_{2^{-k} r_{0}}\right|^{\beta}=\omega_{Q}^{\beta} r_{0}^{\beta Q}\left(\frac{\Gamma}{2^{\beta Q}}\right)^{k}=\left|B_{r_{0}}\right|^{\beta}\left(\frac{\Gamma}{2^{\beta Q}}\right)^{k} .
$$

We now choose $\beta$ such that $\frac{\Gamma}{2^{\beta Q}}=1$. Then, (3.32) becomes

$$
\begin{equation*}
\int_{B_{r_{0}}} u^{2} \psi(z, t) \mathrm{d} z \mathrm{~d} t \leq\left|B_{r_{0}}\right|^{\beta} \frac{1}{\left|B_{2^{-k} r_{0}}\right|^{\beta}} \int_{B_{2-k_{r_{0}}}} u^{2} \psi(z, t) \mathrm{d} z \mathrm{~d} t . \tag{3.34}
\end{equation*}
$$

Let $k \rightarrow \infty$. Then the right-hand side of (3.34) goes to zero, because of the assumption that $u$ vanishes to infinite order at the origin. We conclude that it must be $u \equiv 0$ in $B_{r_{0}}$.

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